

automated electric press brake



The cell was created with a variety of bending applications in mind, but more specifically **yours!** 





automated electric press brake



# **Short programming time**

With our Fx Cell 3D software, it is possible to program the robot off-line in very short time.

# **Active Fingers**

For an accurate repeatability of the pieces with self-learning mode.

# **Plug and play Bending Cell**

# System completely realized by Euromac

Euromac provides a complete solution, designing and developing every single element of the structure, from the machine and the robot integration, to the software wthat runs the production.

A complete, reliable and friendly-use system.



# The first cell configurable according to your production needs.

We configure the machine to your individual specification:

# MAX - MAX 7 (7 Axes Robot)

Cell for small and medium sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axis backgauge
- Robot Kuka KR10 cybertech nano
- Base of the robot integrated into the machine
- Turnover system
- Double part control
- Loading station with 2 tables of 1200 x 800 mm
- Unloading:
- Palletization on a motorized roller conveyor for Europallet
- Vertical storage up to 10 Europallets (optional)
- Automatic belt with unloading into a box (optional)
- Also available with 7 axes robot (MAX).





# **PLUS**

Cell for small and medium sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge.
- Robot Kuka KR10 cybertech nano.
- Base of the robot integrated into the machine
- Centering table
- Turnover system

### • Double part control

- Loading station with 2 tables of 1200 x 800 mm
- Unloading:
- Palletization on a Europallet
- Automatic belt conveyer together with motorized roller conveyor for multi boxes.

# STANDARD

Cell for small and medium sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR10 cybertech nano
- Base of the robot integrated into the machine
- Turnover system
- Double part control
- Loading station with 2 tables of 1200 x 800 mm
- Unloading:
- Palletization on a Europallet
- Automatic belt conveyer for unloading into a box (optional).





# When productivity needs important performances.

The ideal solution for workpieces up to 1500 x 800 mm. Large-capacity robot, with 2 different unloading configurations that can be modulated based on the customer productivity.

### MAX

Cell for small and medium sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60
- Base of the robot integrated into the machine
- Centering table
- Turnover system
- Double part control
- Loading station with 2 tables of 1500 x 800 mm
- Unloading:
- Vertical storage for 10 Europallet (optional)
- Palletization on a motorized roller conveyor for Europallet
- Boxes for small pieces
- Automatic belt conveyer for unloading into a box (optional).







### **STANDARD**

Cell for small and medium sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60
- Base of the robot integrated into the machine
- · Centering table

- Turnover system
- Double part control
- Loading station with 2 tables of 1500 x 800 mm
- Unloading:
- Palletization on 2 Europallet
- Automatic belt conveyer for unloading into a box (optional).



Think big. Solution for workpieces up to 2500x900 mm with 7-axes KR 60 robot on rail.

Large-scale robot, available in 2 unloading configurations suitable to your productive needs.

## MAX

Cell for medium and large sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60 on rail
- Centering table

• Unloading:

- Turnover system
- Double part control
- Loading station for pieces up to 2500 x 900 mm
- Vertical storage for 10 Europallet (optional)
- Box for small pieces
- Palletization on motorized roller conveyor for Europallet.



### **STANDARD**

Cell for medium and large sized pieces with a high production capacity.

### The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60 on rail
- Centering table

- Turnover system
- Double part control
- Loading station for pieces up to 2500 x 900 mm
- Unloading:
- Palletization on 6 Europallet.

# **SOFTWARE**

**ON LINE Standard software** with parametrized programs.



# **FX CELL Supervisor**

The added value is the extreme ease and speed in making any kind of modification to your work.

With Fx Cell supervisor it is possible to:

- modify all the parameters of the bending cells
- choose the right gripper and activate or deactivate the suction cups
- · select or modify the loading part position
- select or modify the unloading position
- activate or deactivate the double metal sheet control

All this, working directly from the interface of our Fx Soft and without having to change anything from the program.

Everything at your fingertips in a simple and fast way.

**Possibility to put** the robot in parking mode to work in manual mode inside the cell.



# **SOFTWARE**

**OFF LINE FX CELL 3D Software optional** 



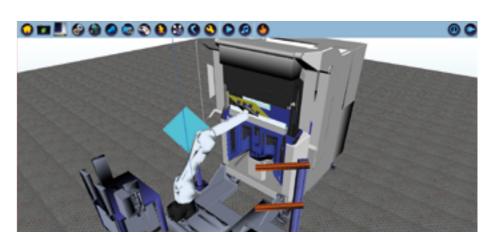


# **Easy and fast** programming time even for more complex requirements.

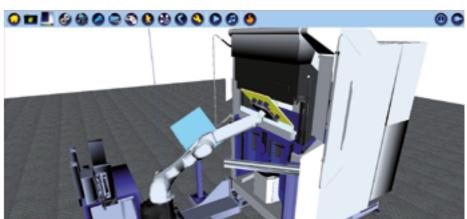
The offline programming software works in perfect cohesion with the FX bend cell, becoming a complementary optional item allowing to quickly anticipate the movements, the processing efficiency and eventually acting to optimize it. Thanks to a 3D graphic display and the management of the palletization data, it's possible to have a complete operation vision and reduce production times.

With Fx Cell 3D software we can assure that in the great majority of the pieces it is not necessary to touch the teaching pad.

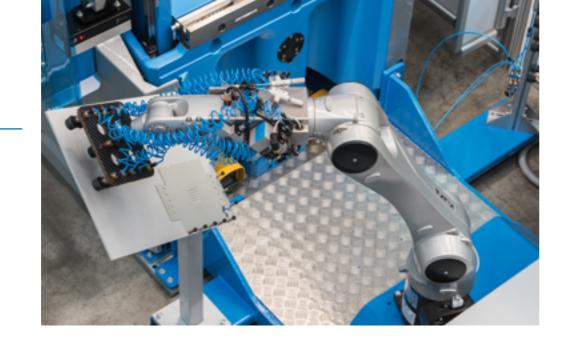
- Reduce production stops due to programming time to a minimum.
- Predict the efficiency of the workcell for any particular product and take action to improve it if necessary.
- Simplify robot programming task.
- Easily visualize and setup palletizing







# **LOADING & UNLOADING**



# **COMBINATION OF UNLOADING** Optional.

Belt conveyer unloading



# **Maximum versatility** of loading - unloading for any production requirement.

When designing a complete system, Euromac also paid great attention to the in-and outbound parts flow, to ensure a fast and reliable production. By anticipating multiple production needs, the FX bend cell offers a wide range of solutions for the loadingunloading operation.

### Loading

Loading area with 2 pre-alignment tables. The pre-alignment table has a perforated die for the perfect positioning

With different loading zones according to the model 1000 x 600, 1500 x 800, 2500 x 1000 mm.

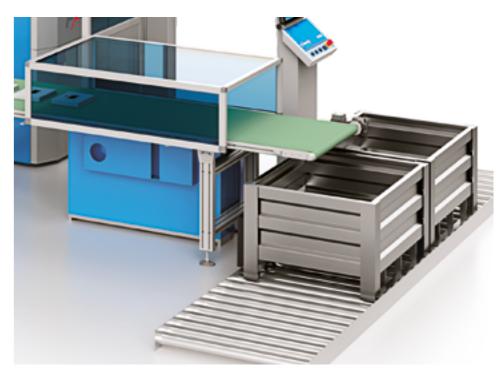
Optionally, we offer the possibility to have additional loading tables, to stack pieces next to a punching or a laser machine, and the easily moved to the cell with a forklift.

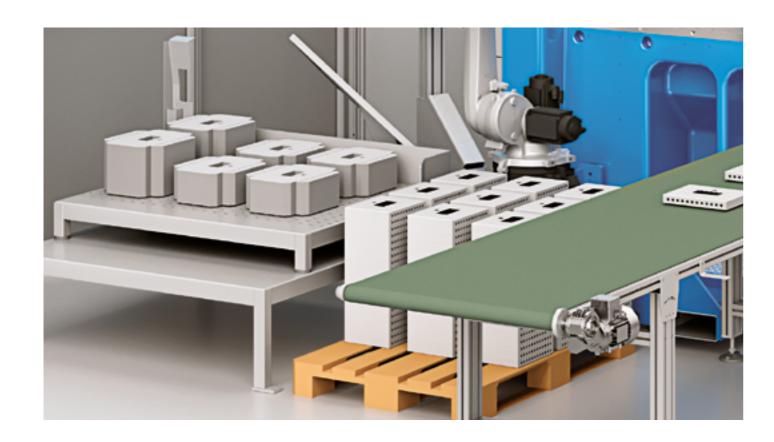
### **Unloading**

Our automated work stations offer many unloading solutions, from palletization of parts on fixed europallets to 10 europallet automatic towers (kit of extra 5 optional pallets), to motorized roller conveyors for fast unloading

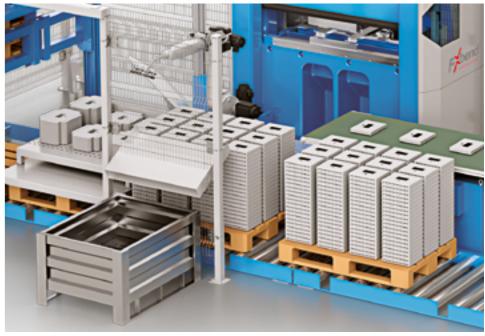
It is also possible to position pieces directly in cases or on a conveyor belt to unload on a fixed case, or positioned on motorized rollers.







**Motorized Europallet** unloading



# **GRIPPERS**

Three examples of standard grippers. Additional gripper to make special customer parts on request.



**Gripper\* with vacuum** for big format parts, external dimension 430x280 with the possibility to insert up to 8 suction cups.

Max nominal part weight: 1.5 Kg (centered position).



**Gripper\* with vacuum** for medium format parts, external dimension 230x230 with the possibility to insert up to 10 suction cups.

Max nominal part weight: 5 Kg (centered position).



**Gripper\* with vacuum** for small parts, with the possibility to insert from 3 up to 20 suction cups divided to maximum 8 independent zones.

Maximum nominal piece weight:

3 Kg. (in centered position).



\*For a real feasibility is necessary to make a supplementary part inertia study where the part geometry is provided by the customer.



# **APPLICATIONS**

Quality and reliability of the pieces for a fast and high quality production.



FX bend cell is an automated bending cell combining production speed with high processing quality.

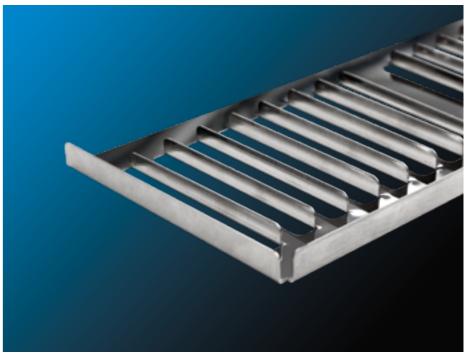


For an accurate repeatability of the pieces with self-learning mode.







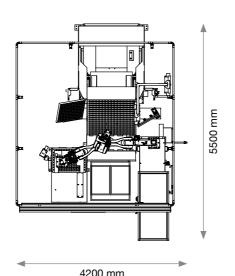






# **STANDARD 1023 / 1547**

technical data	cell <b>1023</b>	cell <b>1547</b>
Max. bending force (kN)	230	470
Bending length (mm)	1020	1530
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	315	360
Promecam clamping (die holder - to ram ) (mm)	395	440
Y axes stroke (mm)	196	240
Y axes speed (mm/sec)	200	200
Max. bending speed automatic mode (mm/sec)	36	36
Max. bending speed manual mode (mm/sec)	10	10
Robot		
Max. reach (mm)	1420	1420
Max. payload with gripper (kg)	10	10
Number of axes	6	6
Pose repeability (mm)	+-0.03	+-0.03
FX Cell		
Loading		
Minimum parts dimension (mm)	50 x 100	50 x 100
Maximum stack height (mm)	300	300
Maximum thicknes (mm)	5	5
Minimum thicknes (mm)	0,7	0,7
Maximum part weight (kg)	5	5
Unloading		
Belt conveyor buffer length (mm)	600 unloading +600	600 unloading +600
Area for gravity unloading (mm)	1200 x 800	1200 x 800
Connected load (kWa)	5	6
Approx. weight (kg)	3000	5000

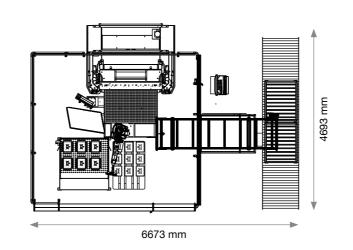


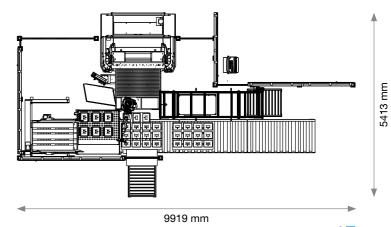


technical data	cell <b>1023</b>	cell <b>1547</b>
Max. bending force (kN)	230	470
Bending length (mm)	1020	1530
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	315	360
Promecam clamping (die holder - to ram ) (mm)	395	440
Y axes stroke (mm)	196	240
Y axes speed (mm/sec)	200	200
Max. bending speed automatic mode (mm/sec)	36	36
Max. bending speed manual mode (mm/sec)	10	10
Robot		
Max. reach (mm)	1420	1420
Max. payload with gripper (kg)	10	10
Number of axes	6	6
Pose repeability (mm)	+-0.03	+-0.03
FX Cell		
Loading		
Minimum parts dimension (mm)	50 x 100	50 x 100
Maximum stack height (mm)	300	300
Maximum thicknes (mm)	5	5
Minimum thicknes (mm)	0,7	0,7
Maximum part weight (kg)	5	5
Unloading		
Belt conveyor buffer length (mm)	600 unloading +600	600 unloading +600
Area for gravity unloading (mm)	1200 x 800	1200 x 800
Connected load (kWa)	5	6
Approx. weight (kg)	3000	5500



technical data	cell <b>1023</b>	cell <b>1547</b>
Max. bending force (kN)	230	470
Bending length (mm)	1020	1530
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	315	360
Promecam clamping (die holder - to ram ) (mm)	395	440
Y axes stroke (mm)	196	240
Y axes speed (mm/sec)	200	200
Max. bending speed automatic mode (mm/sec)	36	36
Max. bending speed manual mode (mm/sec)	10	10
Robot		
Max. reach (mm)	1420	1420
Max. payload with gripper (kg)	10	10
Number of axes	6	6
Pose repeability (mm)	+-0.03	+-0.03
FX Cell		
Loading		
Minimum parts dimension (mm)	50 x 100	50 x 100
Maximum stack height (mm)	300	300
Maximum thicknes (mm)	5	5
Minimum thicknes (mm)	0,7	0,7
Maximum part weight (kg)	5	5
Unloading		
Belt conveyor buffer length (mm)	600 unloading +600	600 unloading + 600
Area for gravity unloading (mm)	1200 x 800	1200 x 800
Connected load (kWa)	5	6
Approx. weight (kg)	3000	6000

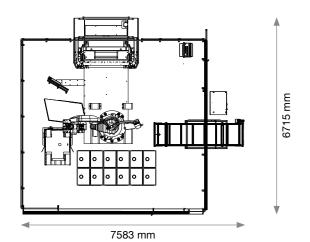






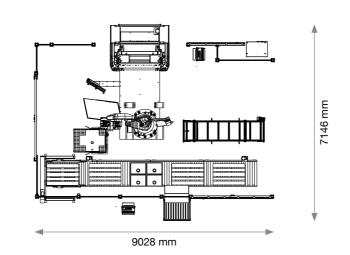
# **STANDARD KR60**

technical data	cell <b>1547</b>	
Max. bending force (kN)	470	
Bending length (mm)	1530	
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	360	
Promecam clamping (die holder - to ram ) (mm)	440	
Y axes stroke (mm)	240	
Y axes speed (mm/sec)	200	
Max. bending speed automatic mode (mm/sec)	36	
Max. bending speed manual mode (mm/sec)	10	
Robot		
Max. reach (mm)	2233	
Max. payload with gripper (kg)	60	
Number of axes	6	
Pose repeability (mm)	+-0.06	
FX Cell		
Loading		
Maximum parts dimension 1 stack (mm)	1500 x 800	
Minimum parts dimension (mm)	50 x 100	
Maximum stack height (mm)	300	
Maximum thicknes (mm)	5	
Minimum thicknes (mm)	0,7	
Maximum part weight (kg)	30	
Unloading		
Belt conveyor Max. parts dimension (mm)	1000 x 600 x h 300	
Belt conveyor buffer length (mm)	600 unloading + 600	
Area for gravity unloading (mm)	1200 x 800	
Connected load (kWa)	6	
Approx. weight (kg)	6200	





technical data	cell <b>1547</b>
Max. bending force (kN)	470
Bending length (mm)	1530
Daylight opening	
Wila clamping (die holder - to punch holder) (mm)	360
Promecam clamping (die holder - to ram ) (mm)	440
Y axes stroke (mm)	240
Y axes speed (mm/sec)	200
Max. bending speed automatic mode (mm/sec)	36
Max. bending speed manual mode (mm/sec)	10
Robot	
Max. reach (mm)	2233
Max. payload with gripper (kg)	60
Number of axes	6
Pose repeability (mm)	+-0.06
FX Cell	
Loading	
Maximum parts dimension 1 stack (mm)	1500 x 800
Minimum parts dimension (mm)	50 x 100
Maximum stack height (mm)	300
Maximum thicknes (mm)	5
Minimum thicknes (mm)	0,7
Maximum part weight (kg)	30
Unloading	
Belt conveyor Max. parts dimension (mm)	1000 x 600 x h 300
Belt conveyor buffer length (mm)	600 unloading + 600
Area for gravity unloading (mm)	1200 x 800
Connected load (kWa)	6
Approx. weight (kg)	7000





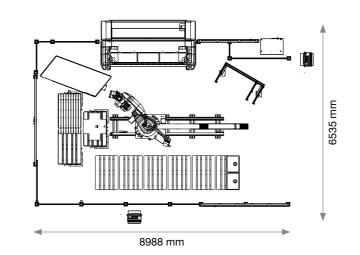
# **STANDARD 2550**

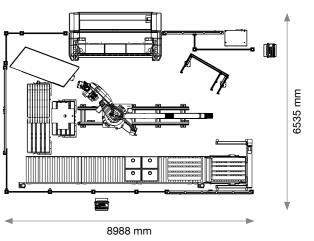
technical data	cell <b>2550</b>
Max. bending force (kN)	500 / 600
Bending length (mm)	2550
Daylight opening	
Wila clamping (die holder - to punch holder) (mm)	360
Promecam clamping (die holder - to ram ) (mm)	440
Y axes stroke (mm)	240
Y axes speed (mm/sec)	200
Max. bending speed automatic mode (mm/sec)	36
Max. bending speed manual mode (mm/sec)	10
Robot	
Max. reach (mm)	2233
Max. payload with gripper (kg)	60
Number of axes	7
Pose repeability (mm)	+-0.06
FX Cell	
Loading	
Maximum parts dimension 1 stack (mm)	2500 x 900
Minimum parts dimension (mm)	50 x 100
Maximum stack height (mm)	300
Maximum thicknes (mm)	5
Minimum thicknes (mm)	0,7
Maximum part weight (kg)	30
Unloading	
Area for gravity unloading (mm)	1200 x 800
Connected load (kWa)	6
Approx. weight (kg)	8500



# **MAX 2550**

technical data	cell <b>2550</b>	
Max. bending force (kN)	500 / 600	
Bending length (mm)	2550	
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	360	
Promecam clamping (die holder - to ram ) (mm)	440	
Y axes stroke (mm)	240	
Y axes speed (mm/sec)	200	
Max. bending speed automatic mode (mm/sec)	36	
Max. bending speed manual mode (mm/sec)	10	
Robot		
Max. reach (mm)	2233	
Max. payload with gripper (kg)	60	
Number of axes	7	
Pose repeability (mm)	+-0.06	
FX Cell		
Loading		
Maximum parts dimension 1 stack (mm)	2500 x 900	
Minimum parts dimension (mm)	50 x 100	
Maximum stack height (mm)	300	
Maximum thicknes (mm)	5	
Minimum thicknes (mm)	0,7	
Maximum part weight (kg)	30	
Unloading		
Area for gravity unloading (mm)	1200 x 800	
Connected load (kWa)	6	
Approx. weight (kg)	9500	







# punching machines



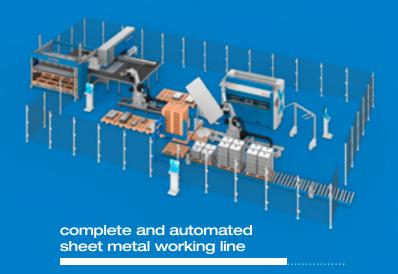


horizontal bending machines



# Euromac meets your ambitions





# EUROM4C.

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